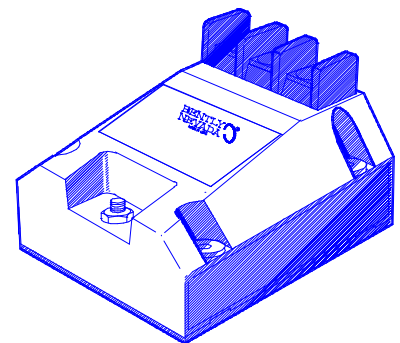


Part number 86130-01
Revision U, November 1999

3300 5 mm and 8 mm PROXIMITY TRANSDUCER SYSTEM

MANUAL

BENTLY
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MADE IN U.S.A.



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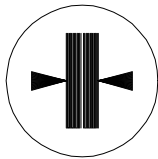
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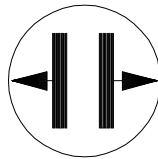
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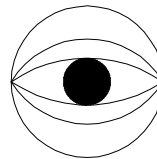
This manual uses the following symbols to indicate actions in maintenance and troubleshooting procedures.



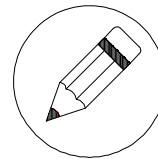
Connect



Disconnect



Observe



Record

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Related Documents

The following documents contain additional information that you may find helpful when you install the transducer.

Installing the Transducer

Best Practices Document - Proximity Probes and Related Accessories: The Installation and Application of Eddy Current Proximity Transducers (AN028).

Guidelines for Grounding (Earthing) Bently Nevada Rotating Machinery Information Systems (AN013).

Installation of Electrical Equipment in Hazardous Areas (AN015).

Transducer Installation Accessories

31000/32000 Proximity Probe Housing Manual (124200-01).

Electrical and Mechanical Runout

“Glitch”: Definition of and Methods for Correction, Including Shaft Burnishing to Remove Electrical Runout (AN002).

API 670, Third Edition, Section 4.1.2: Machine Shaft Requirements for Electrical and Mechanical Runout. Available from the American Petroleum Institute, Publications and Distribution, 1220 L Street NW, Washington DC, 20005, USA.

Reference

Performance Specifications for the 3300 5 mm and 8 mm Transducer System (155687).

Bently Nevada Glossary (133055-01).

European CE Mark for Bently Nevada Proximity Transducer Systems (AN072) (included in this manual).

Section 1 — System Description

The 3300 Series Proximity Transducer System measures machine vibration and the position of a shaft or other machine part relative to the location of the probe tip. The system consists of a 5 mm or 8 mm proximity probe, an extension cable and a Proximator® sensor.

The components of the 3300 Transducer System are designed to work as a single unit and are calibrated for a target material that is AISI 4140 steel. The system measures displacement by using the eddy current principle and provides a negative voltage proportional to the distance between the target and the probe tip. This voltage signal may be applied to a monitor, portable instrumentation or diagnostic equipment.

Application Advisory

The 3300 Proximity Transducer is designed for measuring position or vibration within a frequency range of 0 to 6.5 kHz. Typical applications of this system include radial vibration and position, axial position and Keyphasor® measurements.

Application Alert

Although the terminals and connector on the Proximator® sensor have protection against electrostatic discharge, take reasonable precautions to avoid electrostatic discharge during handling.

Receiving, Inspecting, and Handling the System

The probe, extension cable and Proximator® sensor are shipped as separate units and must be interconnected at the installation site by the user. Carefully remove all equipment from the shipping containers and inspect the equipment for shipping damage. If shipping damage is apparent, file a claim with the carrier and submit a copy to the nearest Bently Nevada office. Include part numbers and serial numbers on all correspondence. If no damage is apparent and the equipment is not going to be used immediately, return the equipment to the shipping containers and reseal until ready for use.

Store the equipment in an environment free from potentially damaging conditions such as high temperature or a corrosive atmosphere. See Specifications, pages 21, 23 and 24 for environmental specifications.

Customer Service

Bently Nevada provides product service throughout the world. If you cannot contact your local product service representative, call the Bently Nevada corporate headquarters:

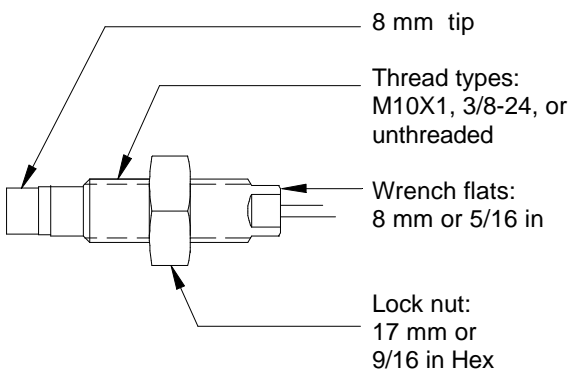
Toll Free from within the United States: 800-227-5514
or from anywhere: 702-782-3611

Section 2 — Installation

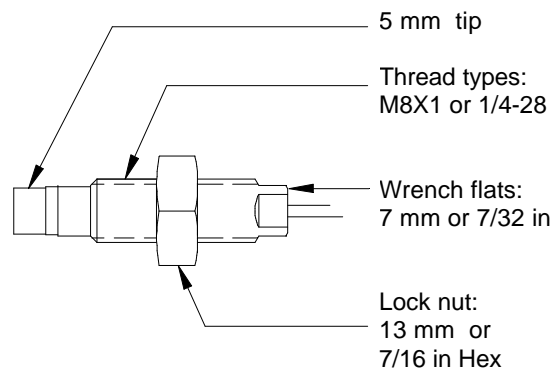
This section contains a checklist of items that you must consider when you install a 3300 Transducer system. For detailed information about designing installations for specific applications refer to document AN028.

Installing the Probe

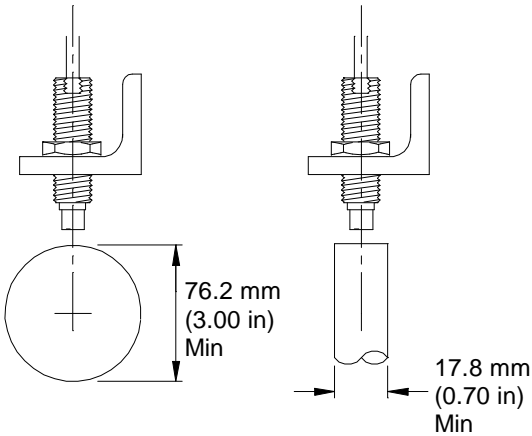
The following figures show the probe sizes and the minimum values for probe separation, side clearance and target configuration. Refer to Specifications for proper torque and the dimensions of the thread.



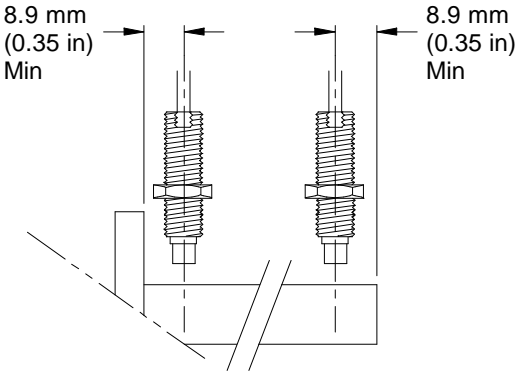
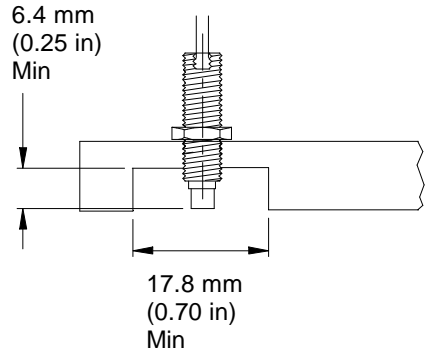
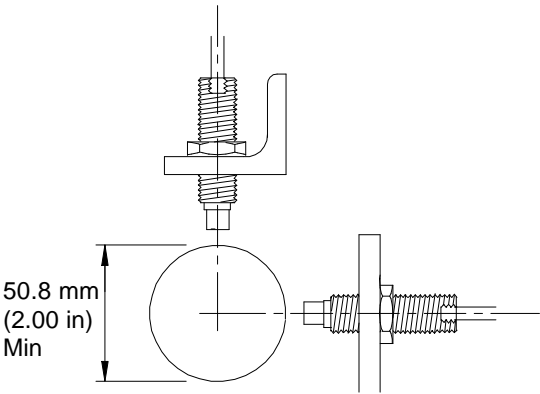
8 mm Probe Sizes



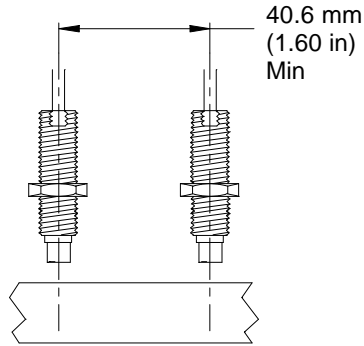
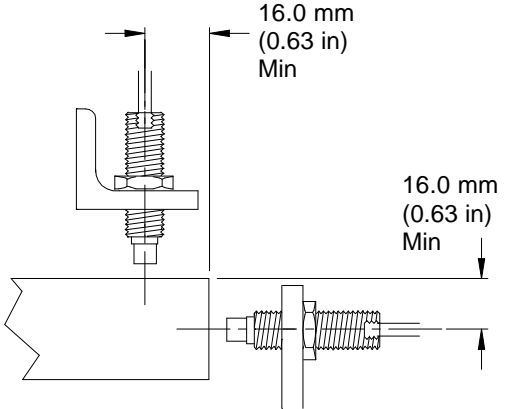
5 mm Probe Sizes



**5 mm & 8 mm Probe
Target Sizes**



**5 mm & 8 mm Probe
Mounting Dimensions**

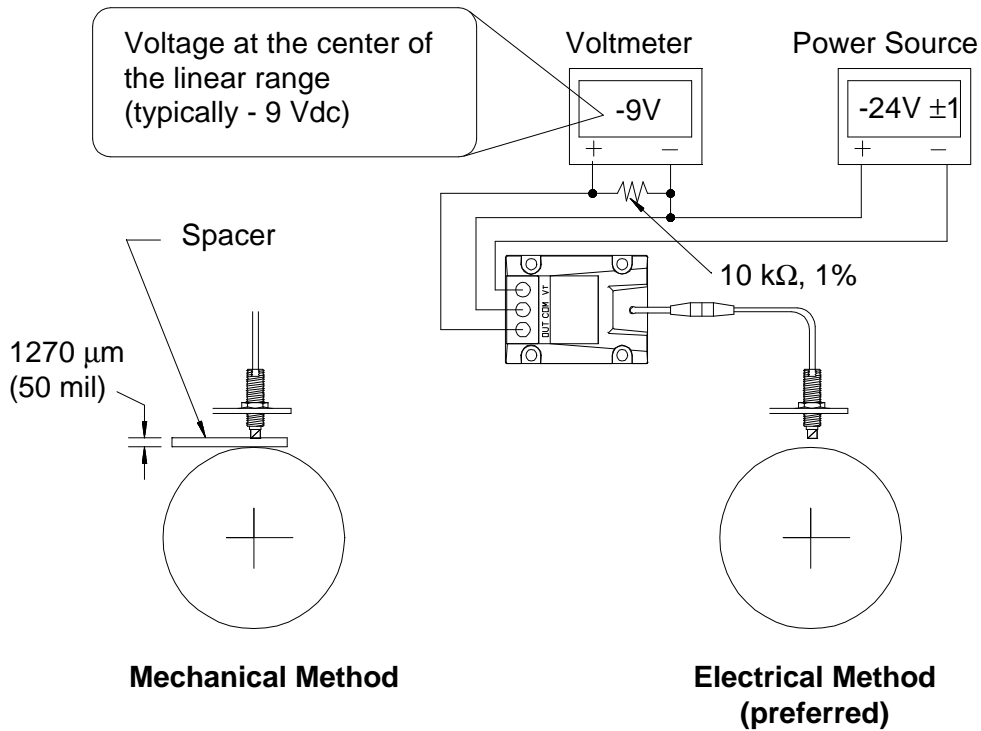


**5 mm & 8 mm Probe-to-Probe
Separation Due to Cross Talk**

Application Alert

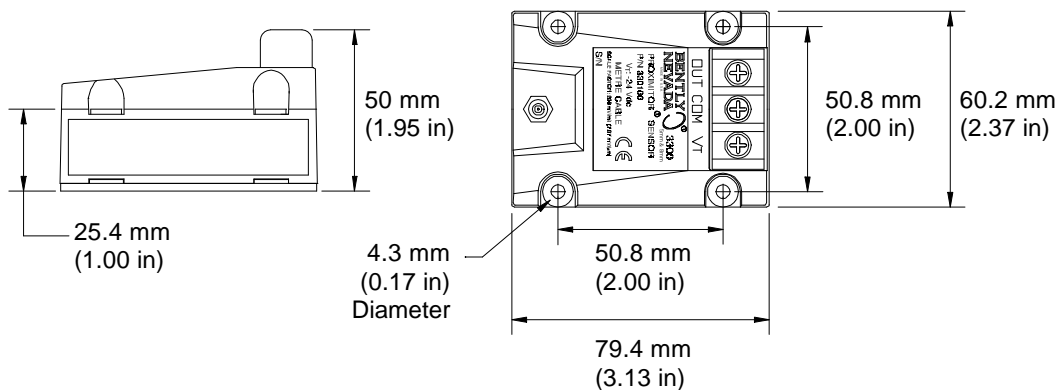
Mounting dimensions and target size affect the scale factor of proximity transducer systems. The minimum recommended dimensions above were chosen to minimize error yet retain flexibility for different mounting situations. Consult performance specification 155687 to determine the effect of each of the above factors for your particular installation.

Adjust the distance between the probe tip and the shaft using one of the methods shown in the following figure. The electrical method for setting the probe gap is preferred. (Refer to document AN028.)



Mounting the Proximator® Sensor

Mount the Proximator® sensor in a location that is compatible with its environmental specifications (page 21). Consider the local electrical codes and the presence of hazardous or explosive gas at the installation site. (Refer to document AN015.)



Routing the Extension Cable and Field Wiring

Route the extension cable using the following guidelines. (Refer to document AN028).

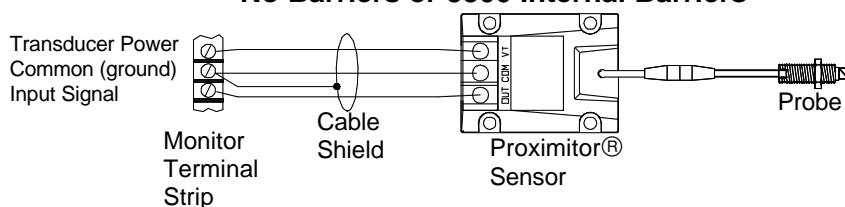
- Check that the extension cable and probe lead length add to equal the Proximitor® sensor system length. (For example, a 9 metre Proximitor® sensor will work with an 8 metre extension cable and a 1 metre probe.)
- Secure the extension cable to supporting surfaces by using mounting clips or similar devices.
- Identify the probe and both ends of the extension cable by inserting labels under the clear Teflon sleeves and applying heat to shrink the tubing.
- Join the coax connectors between the Proximitor® sensor, extension cable and probe lead. Tighten connectors as follows:

Connector Type	Tightening Instruction
Two 3300 XL gold “click” type connectors	Finger tight
Two non-XL connectors (“non-click”) or one non-XL connector and one 3300 XL connector	Finger tight plus 1/8 turn using pliers

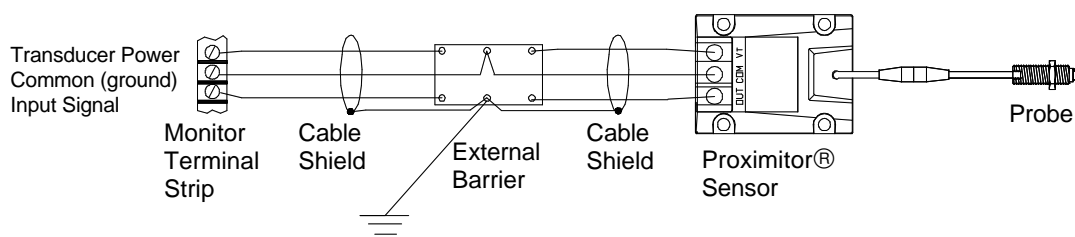
- Use either a connector protector or self-fusing silicone tape to insulate the connection between the probe lead and the extension cable. **DO NOT** use self-fusing silicone tape to insulate a connection made inside of a machine.
- If the probe is in a part of the machine that is under pressure or vacuum, seal the hole where the extension cable leaves the machine by using appropriate cable seals and terminal boxes.

Use the following wiring diagrams to connect the field wiring between the Proximitor® sensor and the monitoring instruments. (Refer to documents AN013 and AN015.)

No Barriers or 3300 Internal Barriers



External Barriers



Section 3 — Maintenance and Troubleshooting

This section shows how to verify that the system is operating properly, adjust the system and identify parts of the system that are not working properly.

The transducer system does not require verification at regular intervals. You should, however, verify operation by using the scale factor verification on page 7 if any of the following conditions occur:

- components of the system are replaced or disturbed
- the performance of the system changes or becomes erratic
- you suspect that the transducer is not calibrated correctly

Use the adjustment procedure on pages 8 through 10 when a special calibration is required. For target materials other than AISI 4140 steel and for other special applications, contact your local Bently Nevada office.

Note: Hazardous Locations
Area must be free of hazardous material before any maintenance or troubleshooting can be performed.

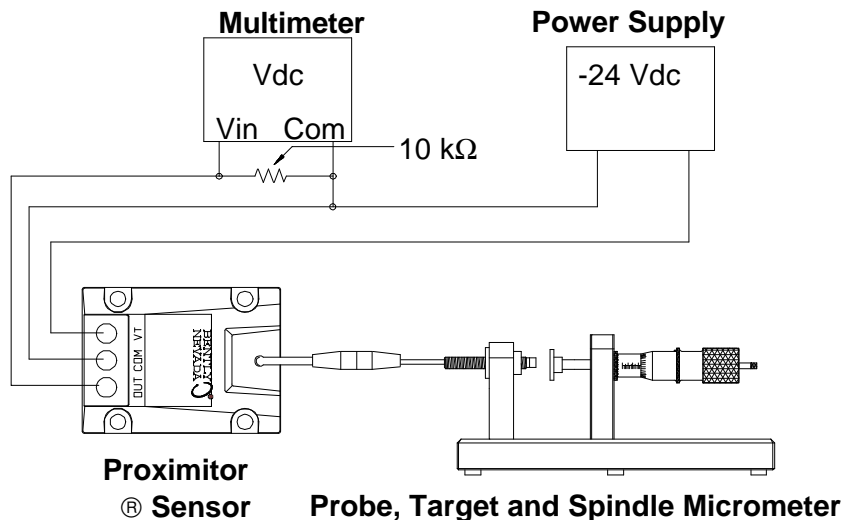
The scale factor verification and the adjustment procedure require the following instruments and equipment:

Digital multimeter spindle micrometer fixed resistor, 10 k Ω 1%
soldering iron and solder power supply (-24Vdc \pm 1)

The special calibration procedure requires the following additional items:

variable resistor, 0 to 100 k Ω
vulcanizing compound (for example, Dow 3110 RTV)

The scale factor verification and the adjustment procedure both use the test setup as shown in the following figure:



Scale Factor Verification

1

460 μm
or
18 mil

500 μm
or
20 mil

Compensate for mechanical backlash and adjust the spindle micrometer for electrical zero.

2

Multimeter

-3.00 ± 0.1 Vdc

Adjust gap to electrical zero by moving the probe.

3

500 μm
or
20 mil

200 μm
or
8 mil

250 μm
or
10 mil

Compensate for mechanical backlash in the micrometer and adjust to the start of the linear range.

4

Multimeter

XXX Vdc

Increments:
250 μm
or
10 mil

n	Adjust Micrometer to...		Record Voltages Vdc _n	Calculate Scale Factor	
	μm _n	or mil _n		ISF _n (Incremental Scale Factor)	ASF (Average Scale Factor)
1	250	10	_____	_____	_____
2	500	20	_____	_____	_____
3	750	30	_____	_____	_____
4	1000	40	_____	_____	_____
5	1250	50	_____	_____	_____
6	1500	60	_____	_____	_____
7	1750	70	_____	_____	_____
8	2000	80	_____	_____	_____
9	2250	90	_____	_____	_____

$$ISF_n \text{ (mV / } \mu\text{m)} = \frac{Vdc_{n-1} - Vdc_n}{0.25}$$

$$ASF_{\text{(mV / } \mu\text{m)}} = \frac{Vdc_{250 \mu\text{m}} - Vdc_{2250 \mu\text{m}}}{2}$$

$$ISF_n \text{ (mV / mil)} = \frac{Vdc_{n-1} - Vdc_n}{0.01}$$

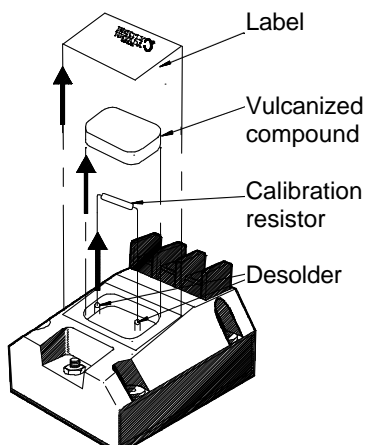
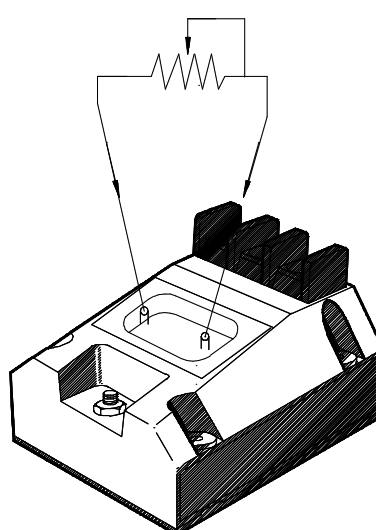
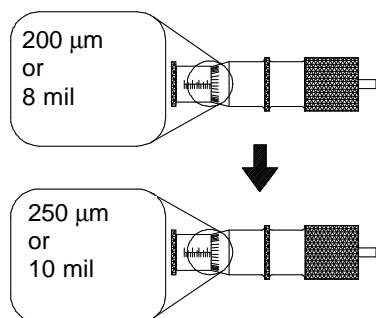
$$ASF_{\text{(mV / mil)}} = \frac{Vdc_{10 \text{ mil}} - Vdc_{90 \text{ mil}}}{0.08}$$

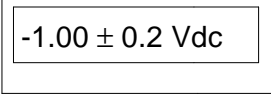
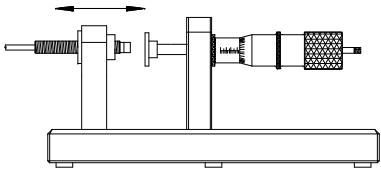
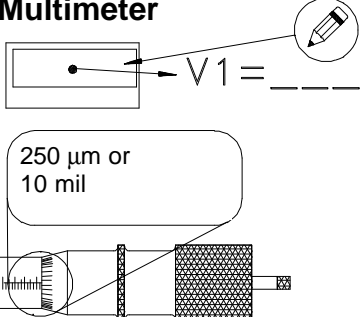
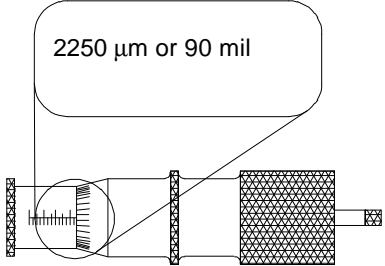
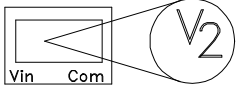
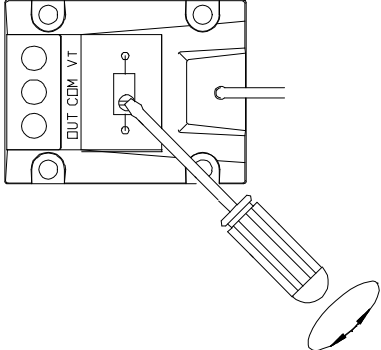
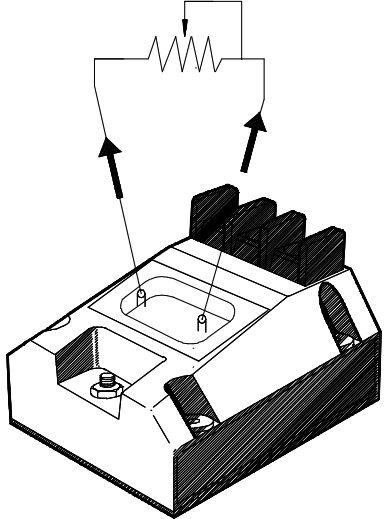
If the incremental scale factor (ISF) or the average scale factor (ASF) of the system is out of tolerance, contact Bently Nevada Corporation for further information on possible calibration problems or perform the following adjustment.

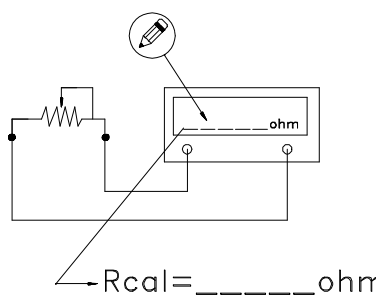
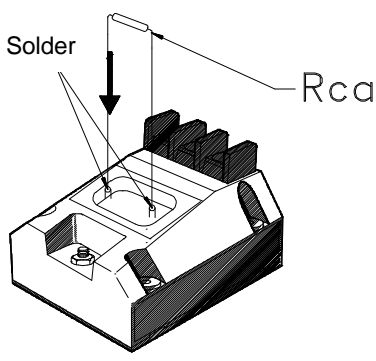
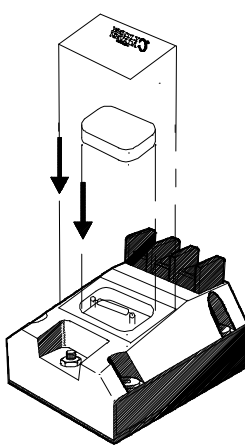
Adjustment Procedure

Application Alert

Electrostatic discharge on the exposed calibration resistor terminals can cause the accuracy of the system to go out of specification or cause the system to fail. Use a grounding strap or equivalent precaution during this procedure.

<p>1</p>  <p>Label Vulcanized compound Calibration resistor Desolder</p> <p>Use a grounded tip soldering iron with less than a 60 watt rating. Leave the iron in contact with the Proximitor® sensor terminal for less than 10 seconds.</p>	<p>2</p> <p>Attach a 0 to 100 kΩ variable resistor.</p> 	<p>3</p>  <p>200 μm or 8 mil</p> <p>250 μm or 10 mil</p> <p>Compensate for mechanical backlash in the micrometer and adjust to start of the linear range.</p>
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<p>4</p> <p>Multimeter</p>   <p>Adjust gap by moving the probe for an output of -1.00 ± 0.20 Vdc.</p>	<p>5</p> <p>Multimeter</p>  <p>250 μm or 10 mil</p>	<p>6</p>  <p>2250 μm or 90 mil</p> <p>Set micrometer to end of the linear range.</p>
<p>7</p> <p>Multimeter</p>   <p>Adjust the variable resistor until the measured voltage (V2) equals</p> <p>$(- V_1 - 16 \text{ Vdc}) \pm 0.16 \text{ Vdc}$</p>	<p>8</p> <p>Repeat steps 3 through 7 until the variable resistor is not changed.</p>	<p>9</p>  <p>Remove variable resistor.</p>

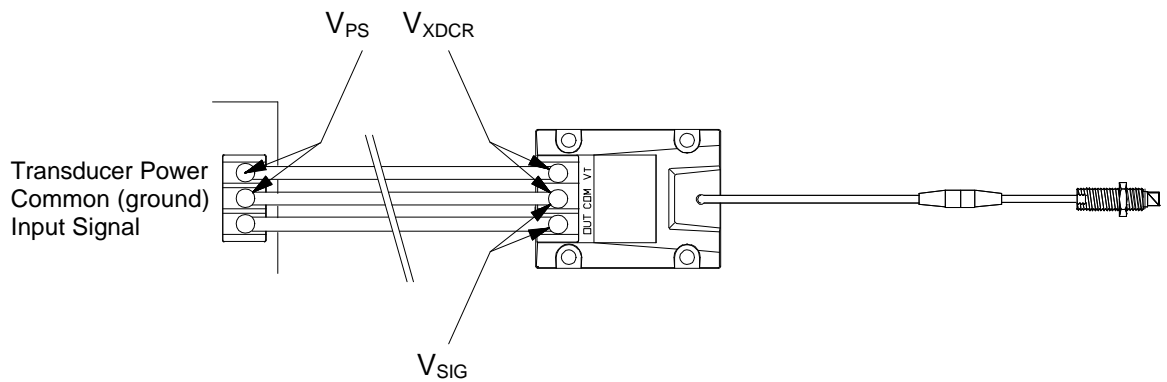
<p>10</p>  <p>Measure and record variable resistor value.</p>	<p>11</p>  <p>Select a fixed calibration resistor (R_{cal}) based on the variable resistor value. The calibration resistor must have a tolerance of $\pm 1\%$ or better. Solder into place.</p>	<p>12</p>  <p>Let cool 10 minutes then perform scale factor verification test.</p>
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Troubleshooting

This section shows how to interpret a fault indication and isolate faults in an installed transducer system. Before beginning this procedure, be sure the system has been installed correctly and all connectors have been secured properly in the correct locations.

When a malfunction occurs, locate the appropriate fault, check the probable causes for the fault indication, and follow the procedure to isolate and correct the fault. Use a digital voltmeter to measure voltage. If you find faulty transducers, contact your local Bently Nevada Corporation office for assistance.

The troubleshooting procedures use measured voltages as shown in the following figure and tables:



Symbols for Measured Voltages

Symbol	Meaning	Voltage measured between...
V_{SIG}	Signal voltage from the transducer	OUT and COM
V_{PS}	Power supply voltage	Power Source and Common
V_{XDCR}	Supply voltage at transducer	-VT and COM

Note: V_{SIG} , V_{PS} , and V_{XDCR} are all negative voltage values.

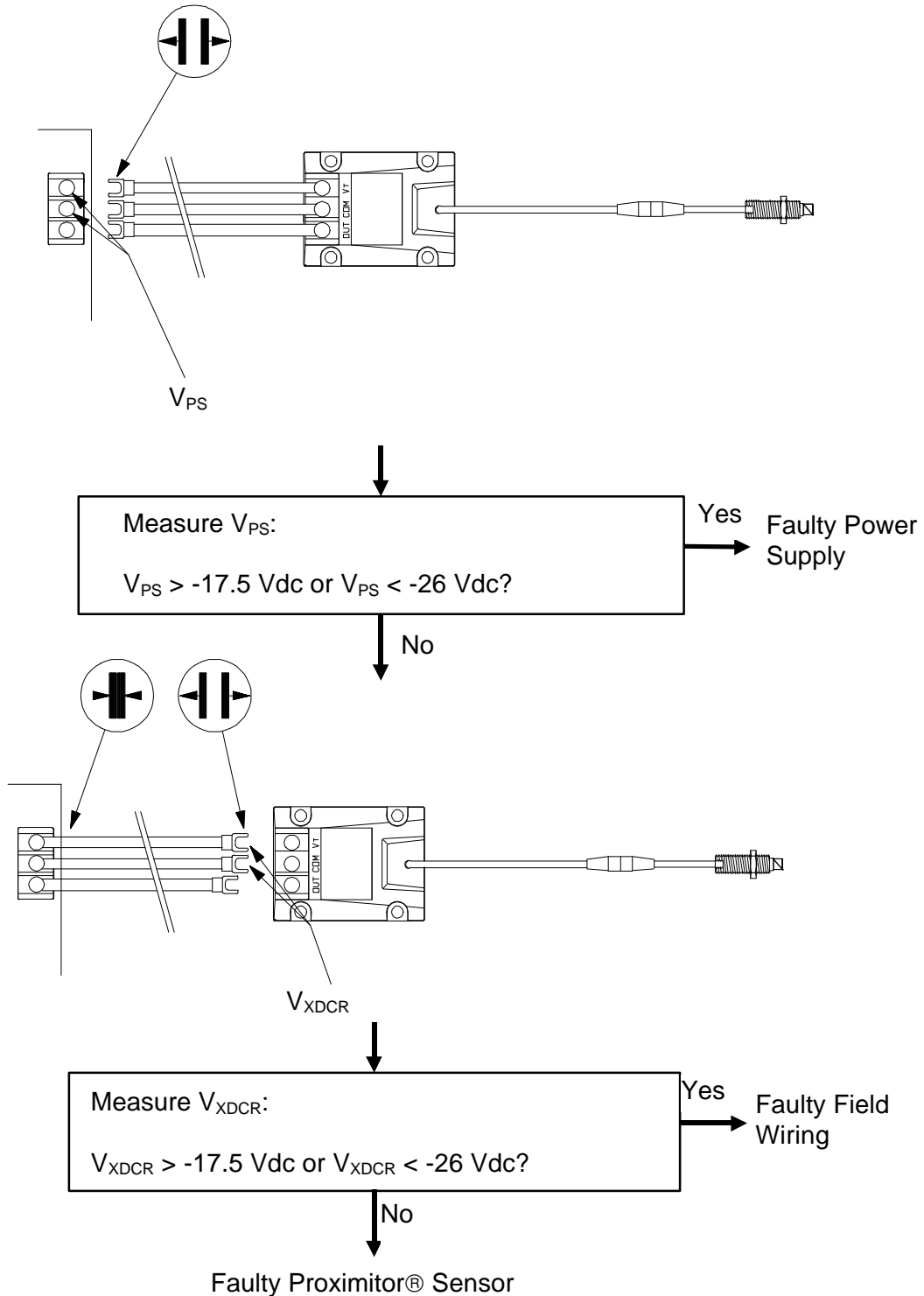
Definitions

Symbol	Definition	Example
$A > B$	"A" value is more positive than "B"	-21 > -23
$A < B$	"A" value is more negative than "B"	-12 < -5
$A = B$	"A" same value (or very close) to "B"	-24.1 = -24.0

Fault Type 1: $V_{XDCR} > -17.5 \text{ Vdc}$ or $V_{XDCR} < -26 \text{ Vdc}$

Possible causes:

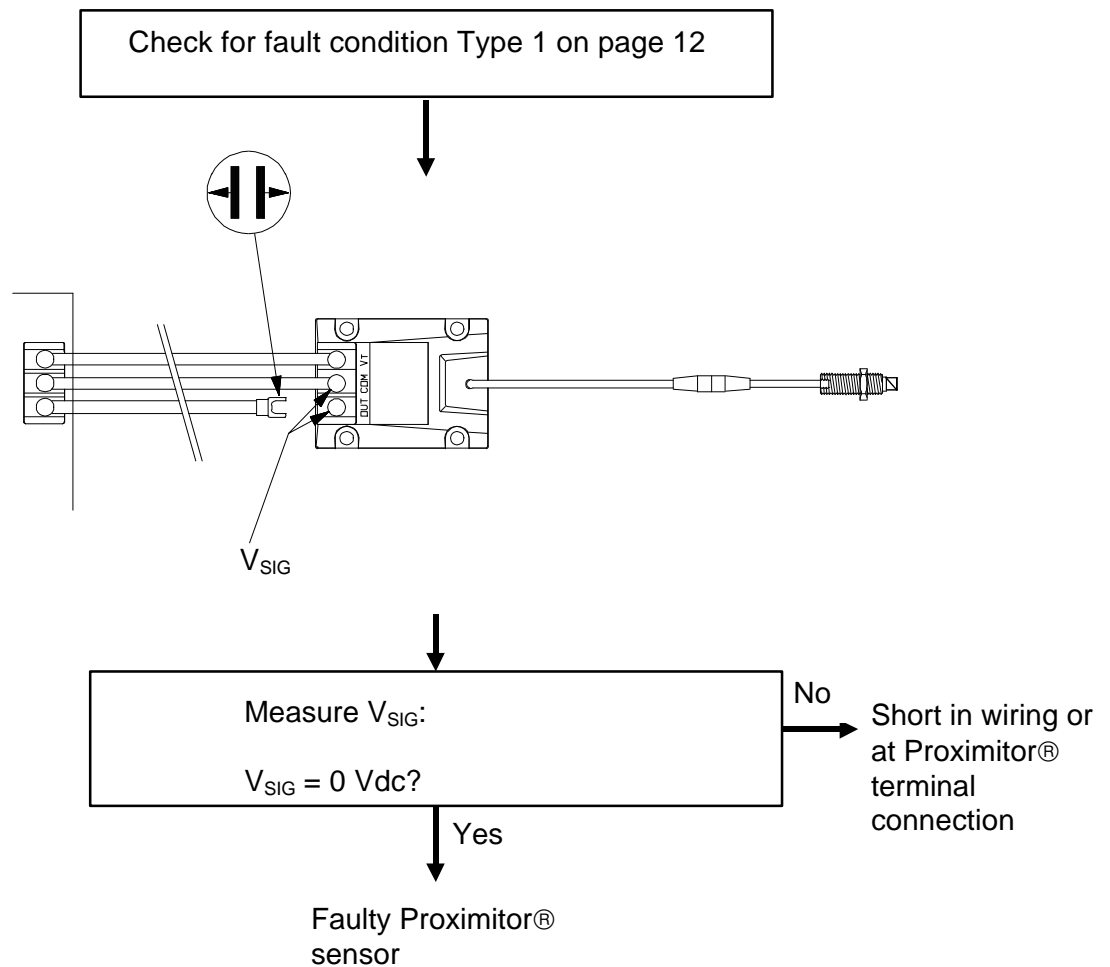
- Faulty power source
- Faulty field wiring
- Faulty Proximito[®]r sensor



Fault Type 2: $V_{SIG} = 0$ Vdc

Possible causes:

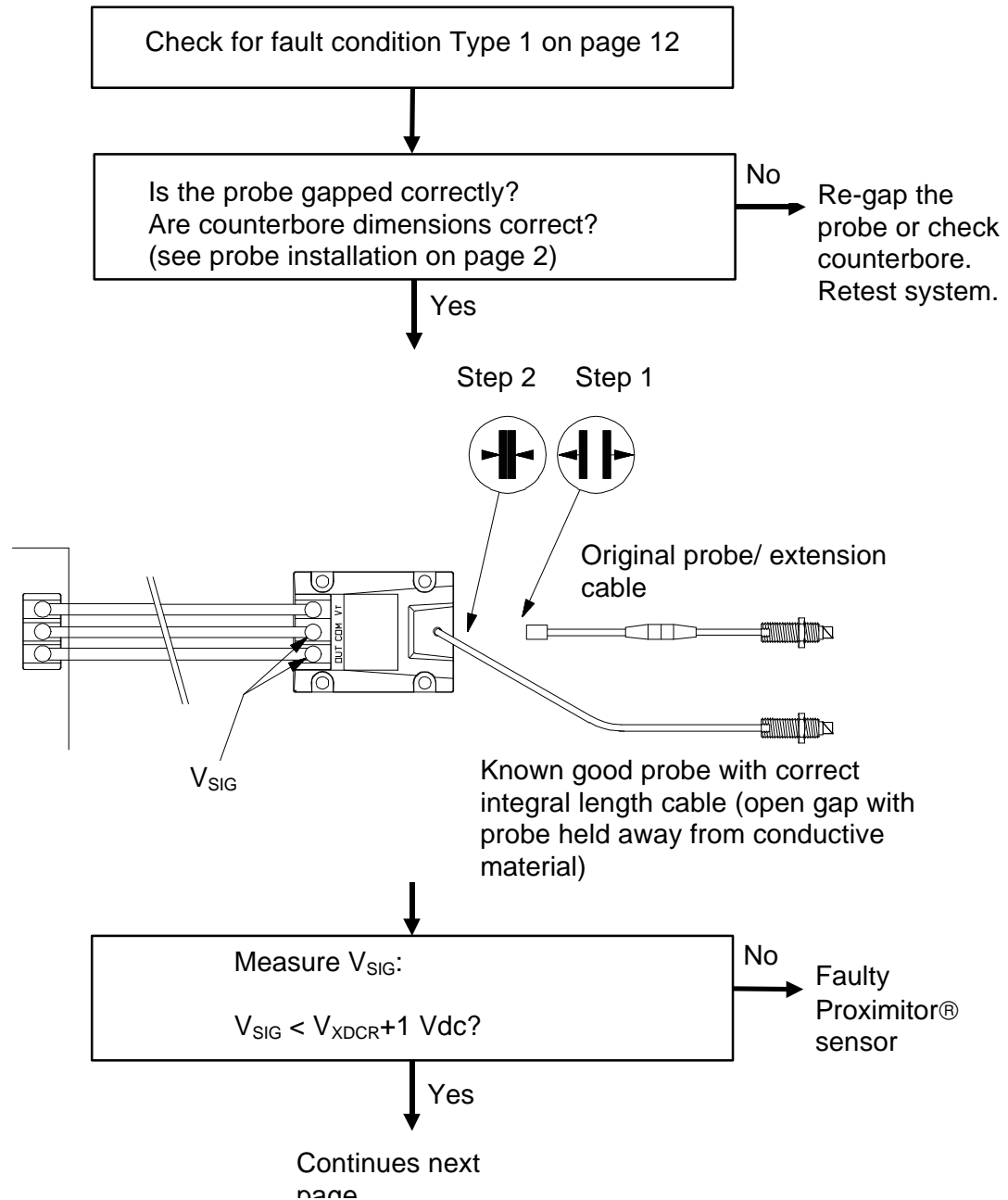
- Incorrect power source voltage
- Short circuit in field wiring
- Short circuit at Proximitor® sensor terminal connection
- Faulty Proximitor® sensor

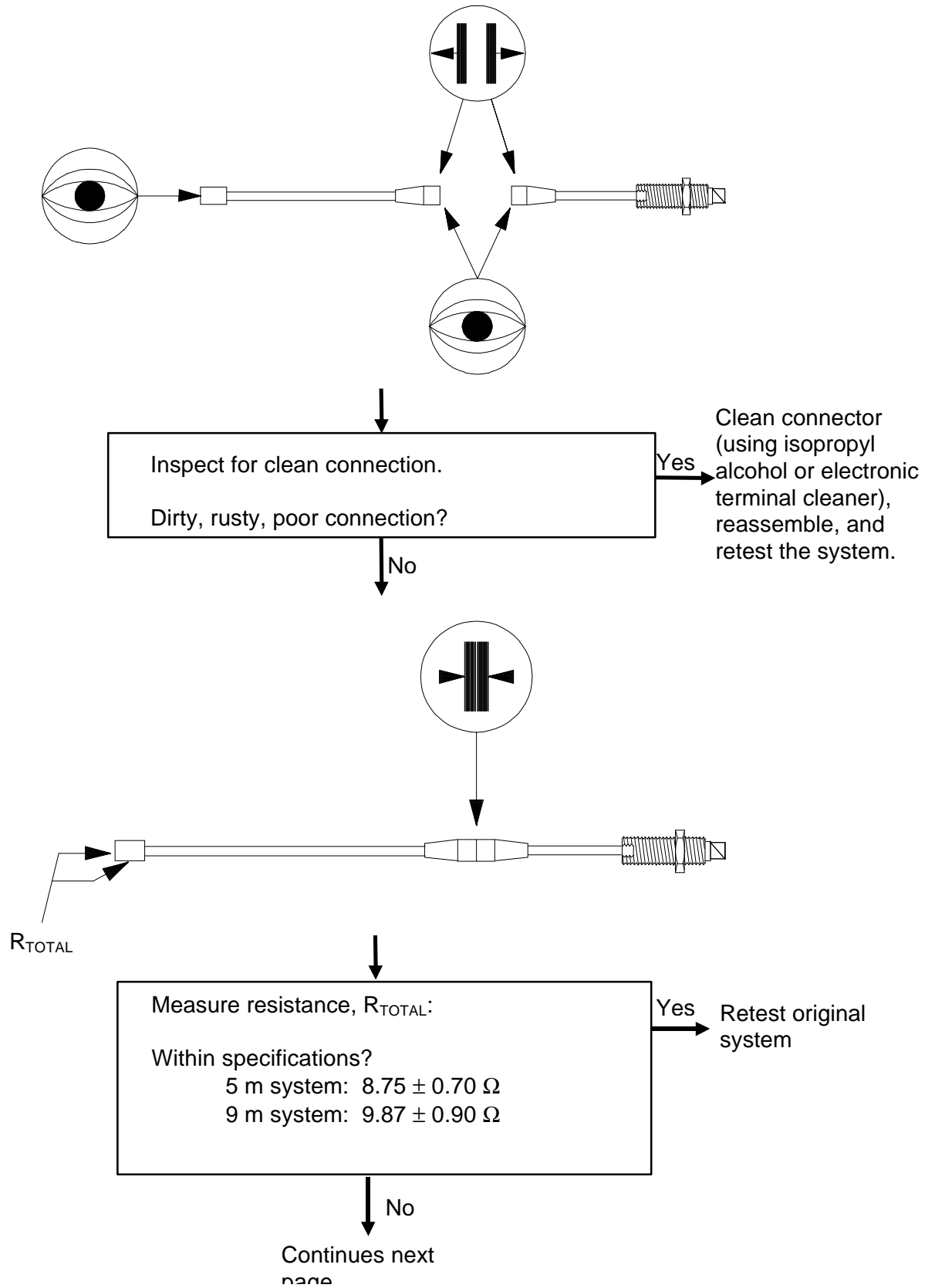


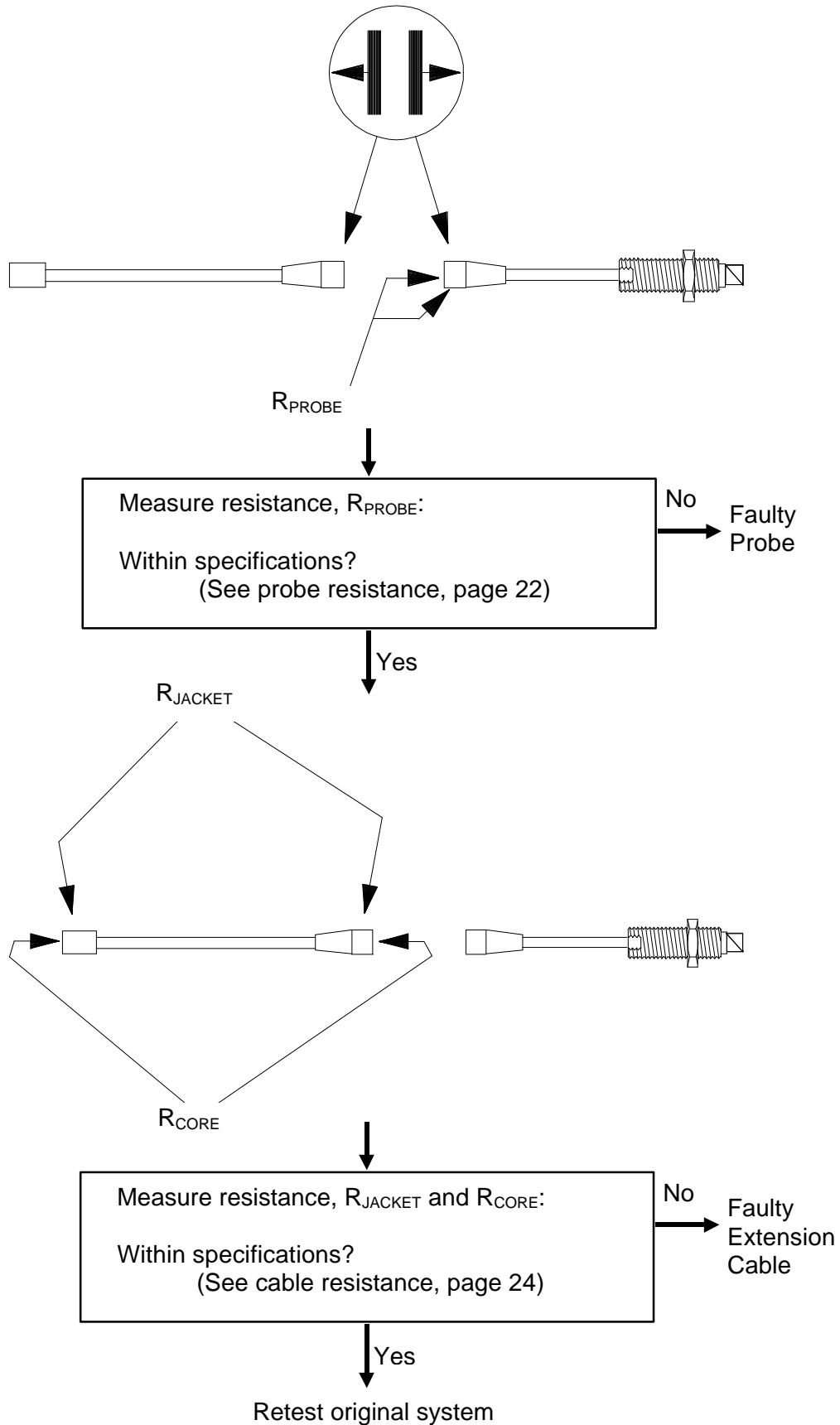
Fault Type 3: $-1 \text{ Vdc} < V_{\text{SIG}} < 0 \text{ Vdc}$

Possible causes:

- Probe is incorrectly gapped (too close to target)
- Incorrect power source voltage
- Faulty Proximator® sensor
- Probe is detecting other material than target (counterbore or machine case)
- Short or open circuit in a connector (dirty or wet) or loose connectors
- Short or open circuit in the probe
- Short or open circuit in extension cable



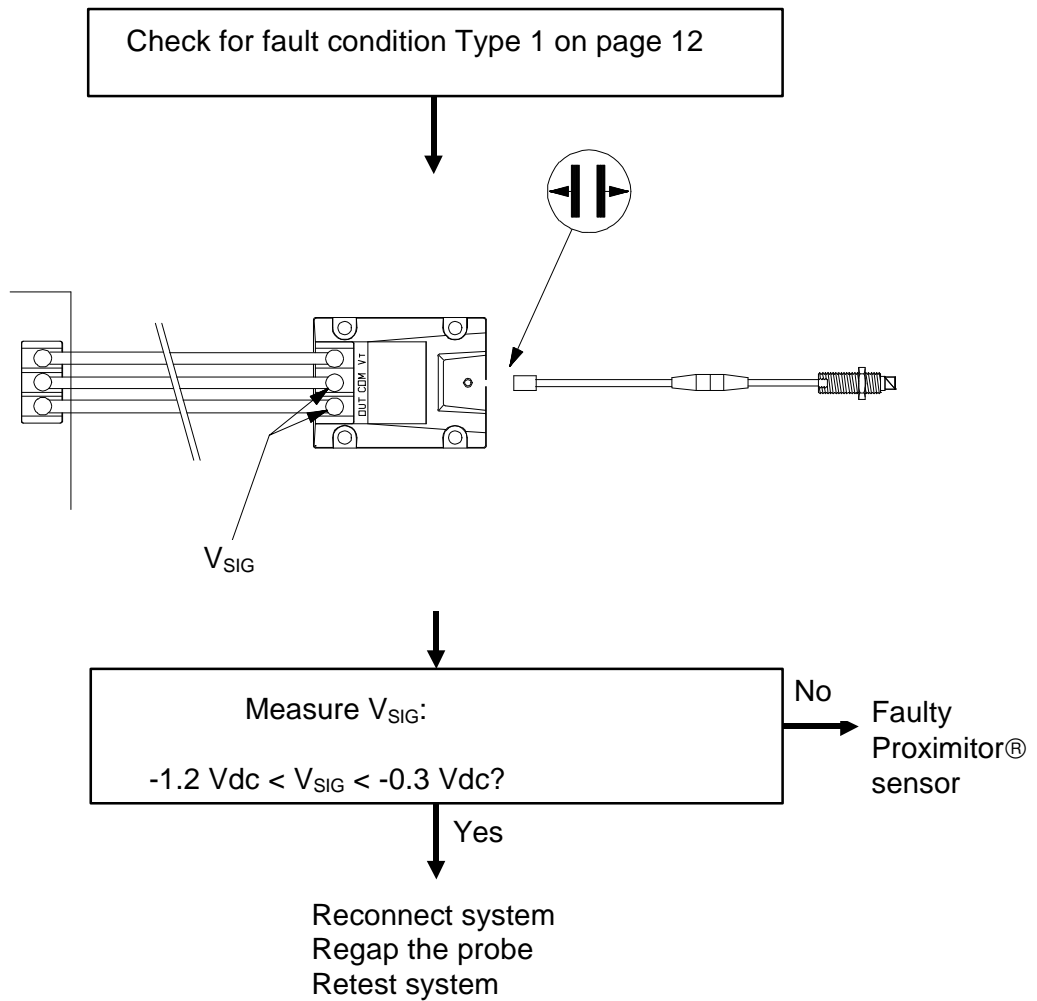




Fault Type 4: $V_{XDCR} < V_{SIG} < V_{XDCR} + 2.5 \text{ Vdc}$

Possible causes:

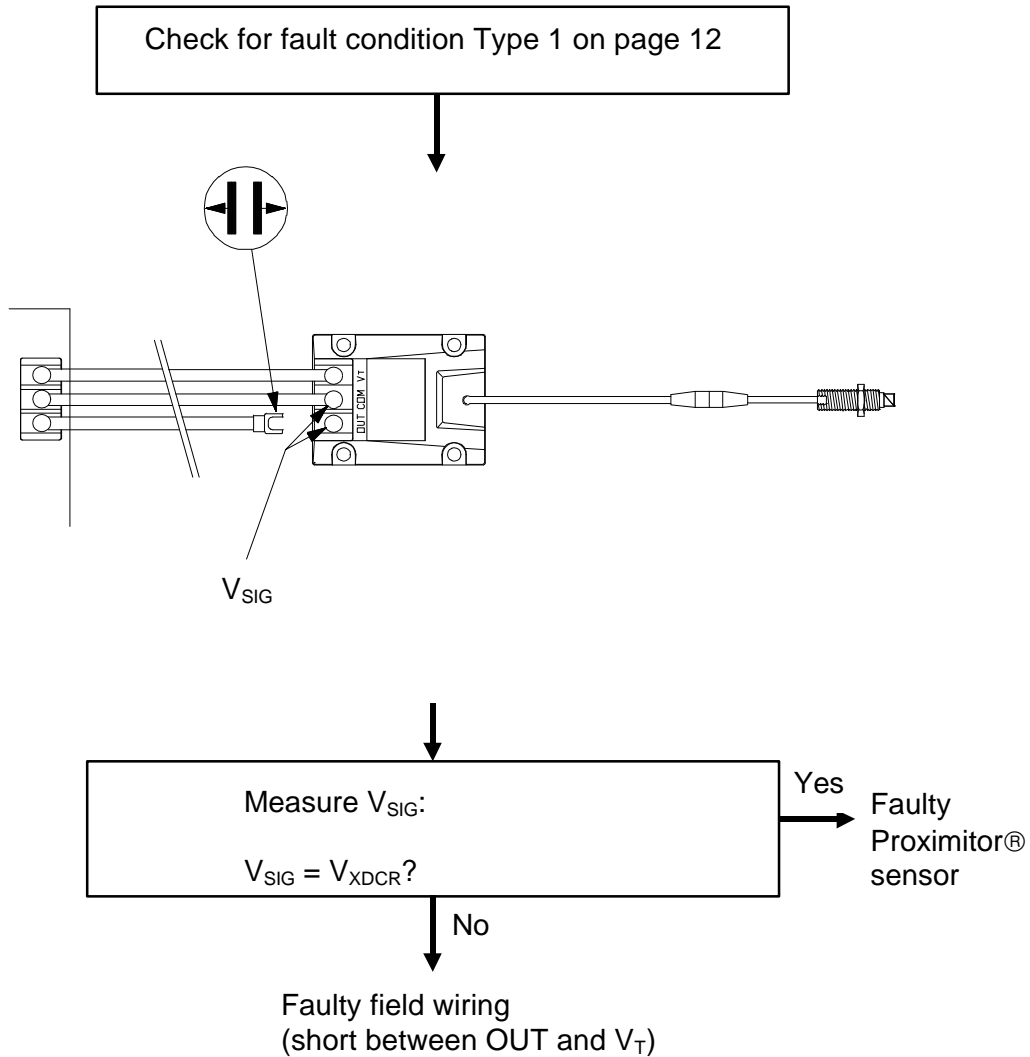
- Faulty Proximator® sensor
- Probe is incorrectly gapped (too far from target)



Fault Type 5: $V_{SIG} = V_{XDCR}$

Possible causes:

- Incorrect power source voltage
- Faulty Proximito[®]r sensor
- Faulty field wiring (between Out and V_T)



Bently Nevada is very concerned when a part fails. Please return the part with a brief note to our corporate headquarters in Minden, Nevada for analysis if you encounter a part that has failed.

Bently Nevada Corporation
Attn: Product Repair Department
1617 Water Street
Minden, Nevada 89423 USA

Section 4 — Specifications

The following specifications apply from 18°C to 27°C (64°F to 80°F) with a Bently Nevada supplied AISI 4140 steel target. Typical is defined as 90% of the devices built meeting the specification, and worst case is defined as 99.7% of the devices built meeting the specification. The calibration range is defined as the 2000 μ m (80 mil) range from 250 μ m (10 mil) below -3.0 Vdc to 1750 μ m (70 mil) above -3.0 Vdc. This range is approximately equivalent to a calibration range of 250 μ m (10 mil) to 2250 μ m (90 mil). ASF refers to the Average Scale Factor over the calibration range, and ISF refers to the Incremental Scale Factor, derivative, over the calibration range as measured in 250 μ m (10 mil) increments.

Application Alert

Operation outside the specified limits will result in false readings, damage to the transducer system and/or loss of machine monitoring.

System

Average Scale Factor (ASF)

Typical	7.87 \pm 0.21 mV/ μ m (200.0 \pm 5.4 mV/mil)
Worst case	7.87 \pm 0.39 mV/ μ m (200.0 \pm 10.0 mV/mil)
Bench calibration	Can be adjusted with the Proximator® sensor calibration resistor for exactly 7.87 mV/ μ m (200.0 mV/mil).

Incremental Scale Factor (ISF)

Typical	7.87 \pm 0.51 mV/ μ m (200.0 \pm 13 mV/mil)
Worst case	7.87 \pm 0.75 mV/ μ m (200.0 \pm 19 mV/mil)
Bench calibration	7.87 \pm 0.31 mV/ μ m (200.0 \pm 8 mV/mil)

Deviation from Straight Line (DSL)

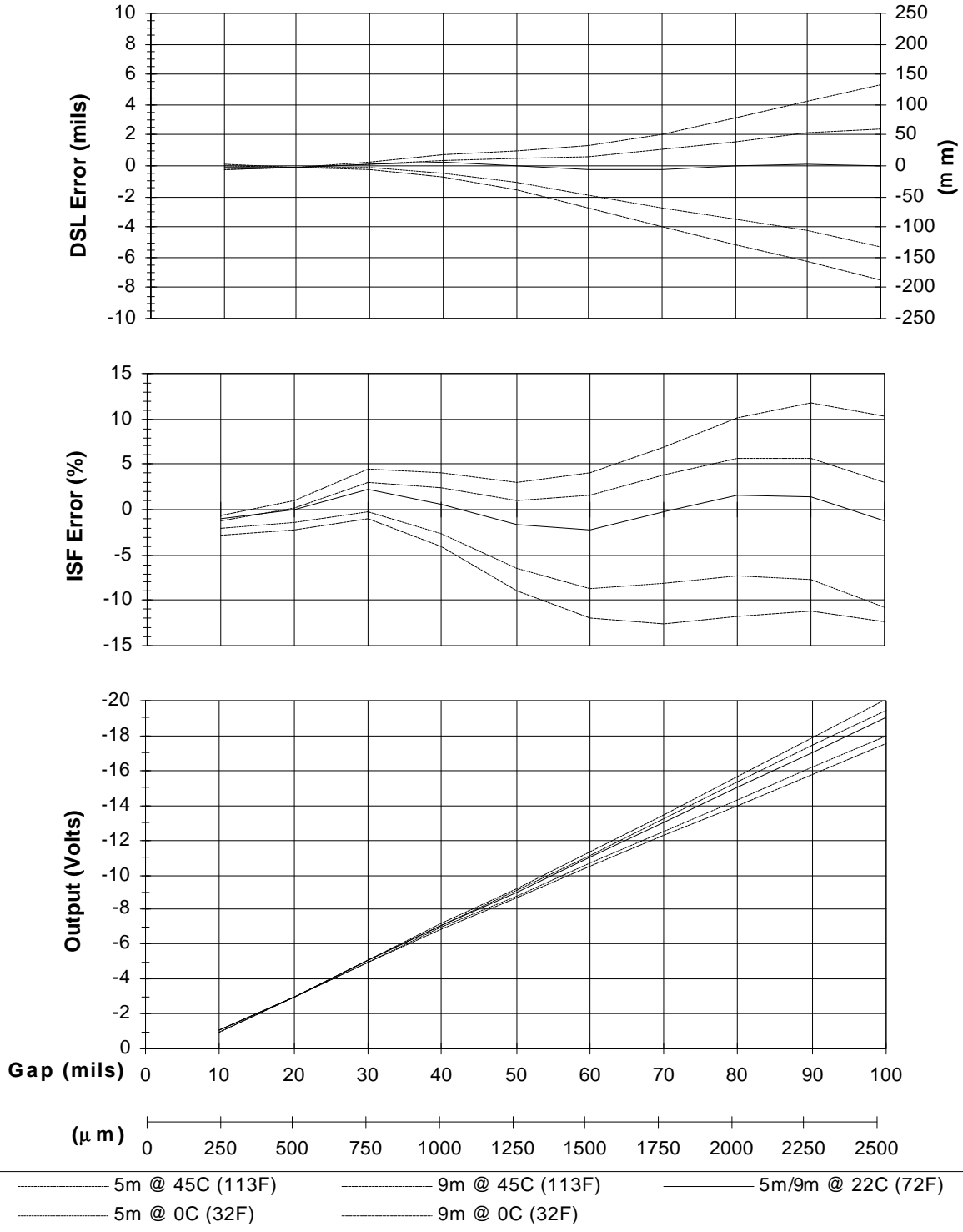
This specification covers a range starting at the beginning of the calibration range and ending 250 μ m (10 mil) after the end of the calibration range. Error is referenced to the straight line which is centered to yield minimum error and which has a 7.87 mV/ μ m (200 mV/mil) slope over the calibration range.

Typical	Less than \pm 38 μ m (1.5 mil)
Worst case	Less than \pm 58 μ m (2.3 mil)
Bench calibration (worst case)	Less than \pm 20 μ m (0.8 mil)

Frequency Response

Typical

0 to 6.5 kHz (390,000 cpm), -3db



Typical Transducer System Curve

Proximito[®] Sensor

Interchangeability error

Average scale factor (ASF) change

Typical Less than 0.09 mV/ μ m (2.3 mV/mil)

Worst case Less than 0.33 mV/ μ m (8.4 mV/mil)

Apparent gap change

At 1270 μ m (50 mil) 180 μ m (7.1 mil) maximum
gap

At 250 μ m (10 mil) 130 μ m (5.3 mil) maximum
gap

Supply Sensitivity

Less than 2 mV change in output voltage per
volt change in input voltage.

Supply voltage range

-17.5 Vdc to -26 Vdc without barriers
-23 Vdc to -26 Vdc with barriers
(Operation at less than -23.5 Vdc can result in
reduced linear range.)

Current draw

12 mA maximum with 10 k Ω load

Output resistance

50 Ω

Output load

Calibrated into a 10 k Ω load

Weight

255 g (9.0 oz)

Temperature

Storage -51° C to +105° C (-60° F to +221° F)

Operating -51° C to +100° C (-60° F to +212° F)

Relative Humidity

100% condensing nonsubmerged from 2° C to
100° C (35° F to 212° F) when connectors are
protected.

Probe

Interchangeability error

Average scale factor (ASF) change

Typical Less than 0.25 mV/ μ m (6.3 mV/mil)

Worst case Less than 0.42 mV/ μ m (10.8 mV/mil)

Voltage difference at same physical gap (maximum)

At 1270 μ m (50 mil) 4.6 Vdc
gap

At 250 μ m (10 mil) 3.6 Vdc
gap

DC resistance (nominal)
(R_{PROBE}) 7.3 Ω + 0.28 Ω /m (7.3 Ω + 0.087 Ω /ft)
 \pm 0.5 Ω for probes 2.0 metres and less
 \pm 0.7 Ω for 5.0 metre probes
 \pm 0.9 Ω for 9.0 metre probes

Connector torque 0.565 N•m (5 in•lb) maximum
 see page 5 for connector tightening
 recommendations.

Case torque

	<u>Maximum Rated</u>	<u>Recommended</u>
M10X1 or 3/8-24 cases	33.9 N•m (300 in•lb)	11.2 N•m (100 in•lb)
M10X1 or 3/8-24 cases (first three threads)	22.6 N•m (200 in•lb)	7.5 N•m (66 in•lb)
M10X1 or 3/8-24 reverse mount cases	22.6 N•m (200 in•lb)	7.5 N•m (66 in•lb)
M8X1 or 1/4-28 cases	8.5 N•m (75 in•lb)	2.8 N•m (25 in•lb)

Recommended min. bend radius (armored or un-armored cable) 25.4 mm (1.00 in)

Weight 20 g (0.7 oz) typical

Temperature

Storage -34° C to +177° C (-30° F to +350° F)

Operating -34° C to +177° C (-30° F to +350° F)

Relative Humidity

100% condensing nonsubmerged from 2° C to 100° C (35° F to 212° F) when connectors are protected.

Cable

Interchangeability error

Average scale factor (ASF) change

Typical Less than 0.09 mV/ μ m (2.2 mV/mil)

Worst case Less than 0.19 mV/ μ m (4.9 mV/mil)

Apparent gap change

At 1270 μ m (50 mil) gap 145 μ m (5.8 mil) maximum

At 250 μ m (10 mil) gap 100 μ m (4.0 mil) maximum

DC resistance, nominal

Center conductor 0.222 Ω /m (0.067 Ω /ft)
(R_{CORE})

Shield (R_{JACKET}) 0.066 Ω /m (0.020 Ω /ft)

Capacitance 69.9 pF/m (21.3 pF/ft) typical

Recommended min. bend radius (armored or unarmored cable) 25.4 mm (1.0 in)

Connector torque 0.565 N•m (5 in•lb) maximum
see page 5 for connector tightening recommendations.

Weight 45 g/m (0.5 oz/ft)

Temperature

Storage -51° C to +177° C (-60° F to +350° F)

Operating -51° C to +177° C (-60° F to +350° F)

Relative Humidity 100% condensing nonsubmerged from 2° C to 100° C (35° F to 212° F) when connectors are protected.

